Static Program Analysis using Abstract Interpretation

Introduction

Static program analysis consists of automatically discovering properties of a program that hold for all possible execution paths of the program.

Static program analysis is **not**

- Testing: manually checking a property for some execution paths
- Model checking: automatically checking a property for all execution paths

Program Analysis for what?

- Optimizing compilers
- Semantic preprocessing:
 - Model checking
 - Automated test generation
- Program verification

Program Verification

- Check that every operation of a program will never cause an error (division by zero, buffer overrun, deadlock, etc.)
- Example:



Incompleteness of Program Analysis

- Discovering a sufficient set of properties for checking every operation of a program is an undecidable problem!
- Every non trivial behavioral property has (at least) NP complexity
- False positives: operations that are safe in reality but which cannot be decided safe or unsafe from the properties inferred by static analysis.

Precision versus Efficiency

Precision: number of program operations that can be decided safe or unsafe by an analyzer.

- Precision and computational complexity are strongly related
- Tradeoff precision/efficiency: limit in the average precision and scalability of a given analyzer
- Greater precision and scalability is achieved through specialization

Soundness

- What guarantees the soundness of the analyzer results?
- In dataflow analysis and type inference the soundness proof of the resolution algorithm is independent from the analysis specification
- An independent soundness proof precludes the use of test-and-try techniques
- Need for analyzers correct by construction

Abstract Interpretation

- A general methodology for designing static program analyzers that are:
 - Correct by construction
 - Generic
 - Easy to fine-tune
- Scalability is difficult to achieve but the payoff is worth the effort!

The core idea of Abstract Interpretation is the formalization of the notion of approximation

- An approximation of memory configurations is first defined
- Then the approximation of all atomic operations
- The approximation is automatically lifted to the whole program structure

Overview of Abstract Interpretation

- Start with a formal specification of the program semantics (the concrete semantics)
- Construct abstract semantic equations w.r.t. a parametric approximation scheme
- Use general fixpoints algorithms to solve the abstract semantic equations
- Try-and-test various instantiations of the approximation scheme in order to find the best fit

The Methodology of Abstract Interpretation

Methodology



Lattices and Fixpoints

- A lattice (L, ⊑, ⊥, ⊔, ⊤, ⊓) is a partially ordered set (L, ⊑) with:
 - Least upper bounds (u) and greatest lower bounds (u) operators
 - A least element "bottom": ⊥
 - A greatest element "top": ¬
- L is complete if all least upper bounds exist
- A fixpoint X of F: $L \rightarrow L$ satisfies F(X) = X
- We denote by Ifp F the least fixpoint if it exists

Fixpoint Theorems

- Knaster-Tarski theorem: If F: L → L is monotone and L is a complete lattice, the set of fixpoints of F is also a complete lattice.
- Kleene theorem: If F: L → L is monotone, L is a complete lattice and F preserves all least upper bounds then Ifp F is the limit of the sequence:

$$\begin{cases} F_0 = \bot \\ F_{n+1} = F(F_n) \end{cases}$$

Methodology



Concrete Semantics

Small-step operational semantics: (Σ, \rightarrow)

$$s = \langle program point, env \rangle$$

$$s \rightarrow s'$$

Example:

1: n = 0; 2: while n < 1000 do 3: n = n + 1; 4: end 5: exit

 $\langle 1, n \Rightarrow \Omega \rangle \rightarrow \langle 2, n \Rightarrow 0 \rangle \rightarrow \langle 3, n \Rightarrow 0 \rangle \rightarrow \langle 4, n \Rightarrow 1 \rangle$ $\langle 2, n \Rightarrow 1 \rangle \rightarrow \dots \rightarrow \langle 5, n \Rightarrow 1000 \rangle$

Undefined value

Control Flow Graph



Transition Relation

Operational semantics: $\langle \mathbf{i}, \boldsymbol{\epsilon} \rangle \rightarrow \langle \mathbf{i}, [op] \boldsymbol{\epsilon} \rangle$ Semantics of op

Methodology



Collecting Semantics

The collecting semantics is the set of observable behaviours in the operational semantics. It is the starting point of any analysis design.

- The set of all descendants of the initial state
- The set of all descendants of the initial state that can reach a final state
- The set of all finite traces from the initial state
- The set of all finite and infinite traces from the initial state
- etc.

Which Collecting Semantics?

- Buffer overrun, division by zero, arithmetic overflows: state properties
- Deadlocks, un-initialized variables: finite trace properties
- Loop termination: finite and infinite trace properties

State properties

The set of descendants of the initial state s_0 :

$$\mathbf{S} = \{ \mathbf{s} \mid \mathbf{s}_0 \to \dots \to \mathbf{s} \}$$

<u>Theorem:</u> $F : (\wp(\Sigma), \subseteq) \to (\wp(\Sigma), \subseteq)$

$$\mathsf{F}(\mathsf{S}) = \{\mathsf{s}_0\} \cup \{\mathsf{s}' \mid \exists \mathsf{s} \in \mathsf{S} \colon \mathsf{s} \to \mathsf{s}'\}$$

Example

$$S = \{ \langle 1, n \Rightarrow \Omega \rangle, \langle 2, n \Rightarrow 0 \rangle, \langle 3, n \Rightarrow 0 \rangle, \langle 4, n \Rightarrow 1 \rangle, \\ \langle 2, n \Rightarrow 1 \rangle, ..., \langle 5, n \Rightarrow 1000 \rangle \}$$

Computation

- F0 = Ø
- $F1 = \{ \langle 1, n \Rightarrow \Omega \rangle \}$
- $F2 = \{ \langle 1, n \Rightarrow \Omega \rangle, \langle 2, n \Rightarrow 0 \rangle \}$
- F3 = { $\langle 1, n \Rightarrow \Omega \rangle$, $\langle 2, n \Rightarrow 0 \rangle$, $\langle 3, n \Rightarrow 0 \rangle$ }
- $F4 = \{ \langle 1, n \Rightarrow \Omega \rangle, \langle 2, n \Rightarrow 0 \rangle, \langle 3, n \Rightarrow 0 \rangle, \langle 4, n \Rightarrow 1 \rangle \}$
- ...

Methodology



Partitioning

We partition the set S of states w.r.t. program points:

- $\Sigma = \Sigma_1 \oplus \Sigma_2 \oplus ... \oplus \Sigma_n$
- $\Sigma_i = \{ \langle \mathbf{k}, \, \boldsymbol{\epsilon} \rangle \in \Sigma \mid \mathbf{k} = \mathbf{i} \}$
- $F(S_1, ..., S_n)_0 = \{ s_0 \}$
- $F(S_1, ..., S_n)_i = \{s' \in S_i \mid \exists j \exists s \in S_j : s \rightarrow s'\}$

i.e.

 $\mathsf{F}(\mathsf{S}_1,\,...,\,\mathsf{S}_n)_i = \{\langle i, \text{ [op] } \epsilon \rangle \mid (j) \xrightarrow{op} (i) \in \mathsf{CFG} (\mathsf{P})\}$

Illustration



Semantic Equations

- <u>Notation</u>: E_i = set of environments at program point i
- System of semantic equations:

$$\mathbf{E}_{i} = \mathbf{U} \{ [op] E_{j} | \bigcirc \phi \\ \bigcirc \phi$$

• Solution of the system **S** = Ifp **F**

Example

1: n = 0; 2: while n < 1000 do 3: n = n + 1; 4: end 5: exit

$$E_{1} = \{n \Rightarrow \Omega\}$$

$$E_{2} = \llbracket n = 0 \rrbracket E_{1} \cup E_{4}$$

$$E_{3} = E_{2} \cap]-\infty, 9999]$$

$$E_{4} = \llbracket n = n + 1 \rrbracket E_{3}$$

$$E_{5} = E_{2} \cap [1000, +\infty[$$

Example



Methodology





Problem: Compute a sound approximation S[#] of S

Solution: Galois connections

Galois Connection



- $\forall x \forall y : \alpha(x) \le y \iff x \subseteq \gamma(y)$
- $\forall x \forall y : x \subseteq \gamma \circ \alpha (x) \& \alpha \circ \gamma (y) \leq y$

Fixpoint Approximation



Abstracting the Collecting Semantics

• Find a Galois connection:

$$(\wp(\Sigma), \subseteq) \xrightarrow{\gamma} (\Sigma^{\#}, \leq)$$

• Find a function: $\alpha \circ F \circ \gamma \leq F^{\#}$

Abstract Algebra

- <u>Notation:</u> E the set of all environments
- Galois connection:

$$(\wp(\mathsf{E}), \subseteq) \xrightarrow{\gamma} (\mathsf{E}^{\#}, \leq)$$

- \cup , \cap approximated by \cup [#], \cap [#]
- Semantics [op] approximated by [op] #

$$\boldsymbol{\alpha} \circ \boldsymbol{[op]} \circ \boldsymbol{\gamma} \subseteq \boldsymbol{[op]}^{\#}$$

Abstract Semantic Equations

$$1: n = 0;$$

2: while n < 1000 do

$$3: n = n + 1;$$

- 4: end;
- 5: exit;

$$E_{1}^{\#} = \alpha \left(\{n \Rightarrow \Omega\}\right)$$

$$E_{2}^{\#} = [[n = 0]]^{\#} E_{1}^{\#} \cup^{\#} E_{4}^{\#}$$

$$E_{3}^{\#} = E_{2}^{\#} \cap^{\#} \alpha (]-\infty, 999])$$

$$E_{4}^{\#} = [[n = n + 1]]^{\#} E_{3}^{\#}$$

$$E_{5}^{\#} = E_{2}^{\#} \cap^{\#} \alpha ([1000, +\infty[)$$

Methodology



Abstract Domains

Various kinds of approximations:

• Signs (non relational)

 $X \Rightarrow +, y \Rightarrow -, ...$

• Intervals (nonrelational):

 $x \Rightarrow [3, 9], y \Rightarrow [-23, 4], ...$

• Polyhedra (relational):

 $x + y - 2z \le 10, ...$

• Difference-bound matrices (weakly relational):

 $y - x \le 5, z - y \le 10, ...$

Example: intervals

1: n = 0; 2: while n < 1000 do 3: n = n + 1; 4: end 5: exit

- Iteration 1: $E_2^{\#} = [0, 0]$
- Iteration 2: $E_2^{\#} = [0, 1]$
- Iteration 3: $E_2^{\#} = [0, 2]$
- Iteration 4: $E_2^{\#} = [0, 3]$



How to cope with lattices of infinite height?

Solution: automatic extrapolation operators

Methodology



Widening operator

Lattice (L, \leq) : $\nabla : L \times L \rightarrow L$

- Abstract union operator: $\forall x \forall y : x \le x \nabla y \& y \le x \nabla y$
- Enforces convergence: $(x_n)_{n \ge 0}$

$$\begin{cases} y_0 = x_0 \\ y_{n+1} = y_n \nabla x_{n+1} \end{cases}$$

 $(y_n)_{n\geq 0}$ is ultimately stationary

Widening of intervals

- If $a \le a'$ then a else $-\infty$
- If $b' \leq b$ then b else $+\infty$

Open unstable bounds (jump over the fixpoint)

Widening and Fixpoint



Iteration with widening

$$1: n = 0;$$

- 3: n = n + 1;
- **4**: end
- 5: exit

$$(\mathbf{E}_{2}^{\#})_{n+1} = (\mathbf{E}_{2}^{\#})_{n} \nabla \left(\ \left[\mathbf{n} = \mathbf{0} \right] \ ^{\#} (\mathbf{E}_{1}^{\#})_{n} \cup ^{\#} (\mathbf{E}_{4}^{\#})_{n} \right)$$

Iteration 1 (union): $E_2^{\#} = [0, 0]$ Iteration 2 (union): $E_2^{\#} = [0, 1]$ Iteration 3 (widening): $E_2^{\#} = [0, +\infty] \Rightarrow$ stable

Imprecision at loop exit

• $E_5^{\#} = [1000, +\infty[$

Narrowing operator

Lattice (L, \leq) : $\Delta : L \times L \rightarrow L$

• Abstract intersection operator:

$$\forall x \forall y : \ x \cap y \leq x \ \Delta \ y$$

• Enforces convergence: $(x_n)_{n \ge 0}$

$$\begin{cases} y_0 = x_0 \\ y_{n+1} = y_n \Delta x_{n+1} \end{cases}$$

 $(y_n)_{n\geq 0}$ is ultimately stationary

Narrowing of intervals

- If $a = -\infty$ then a' else a
- If $\mathbf{b} = +\infty$ then \mathbf{b}' else \mathbf{b}

→ Refines open bounds

Narrowing and Fixpoint



Iteration with narrowing

$$(\mathbf{E}_{2}^{\#})_{n+1} = (\mathbf{E}_{2}^{\#})_{n} \Delta \left(\ \left[\mathbf{n} = \mathbf{0} \right] \ ^{\#} (\mathbf{E}_{1}^{\#})_{n} \cup ^{\#} (\mathbf{E}_{4}^{\#})_{n} \right)$$

Beginning of iteration: $E_2^{\#} = [0, +\infty[$ Iteration 1: $E_2^{\#} = [0, 1000] \Rightarrow$ stable Consequence: $E_5^{\#} = [1000, 1000]$

Methodology



Tuning the abstract domains

1:
$$n = 0;$$

$$\mathbf{2}: \mathbf{k} = \mathbf{0}$$

- 3: while n < 1000 do
- 4: n = n + 1;

5:
$$k = k + 1;$$

6: end

• Intervals:

 $E_4^{\#} = \langle n \Rightarrow [0, 1000], k \Rightarrow [0, +\infty[\rangle$

• Convex polyhedra:

 $E_4^{\ \#} = \langle \ 0 \le n \le 1000, \ 0 \le k \le 1000, \ n - k = 0 \rangle$

Annotated Bibliography

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